

UAV DASL Antenna

Team D1: Kalli Albright Kaitlyn Barr Dustin Branges Daniel Johnson

October 3, 2017



OVERVIEW

- Project Description
- Background/Benchmarking
- Customer Requirements
- Engineering Requirements
- Designs Considered
- Schedule
- Budget

PROJECT DESCRIPTION

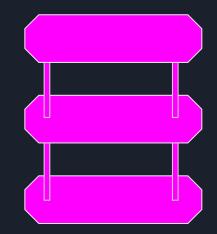
- Dr. Shafer Dynamic and Active Systems Lab (DASL)
- National Science Foundation (NSF)
- Unmanned Aerial Vehicle (UAV) to track wildlife
- Using VHF telemetry tag tracking
- Need to gimbal antenna for better data





BACKGROUND

- Modular octagon housing
- Communication to a Raspberry Pi
- Gimbal antenna to the bottom





BENCHMARKING

- MOOG Antenna Pointing Mechanisms
 - 2 degrees of freedom
 - Made for spacecraft
- Octopus Portable Tracking Antenna
 - Made for tracking UAV from ground
 - Integrated pointing algorithm
- Marcus UAV Retractable Gimbal
 - Retractable camera
 - 180 degree tilt









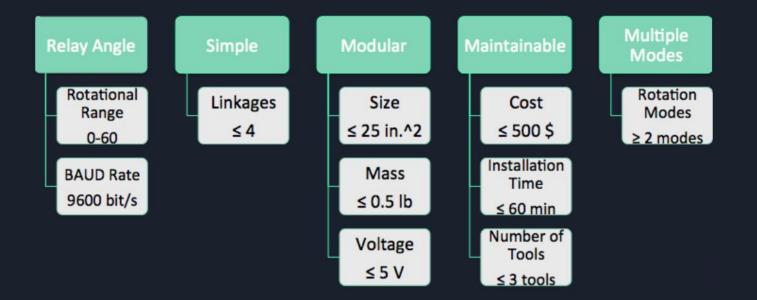
CUSTOMER REQUIREMENTS

- Relay Angle to Customer
- Simple
- Maintainable
- Modular
- Multiple Modes of Movement



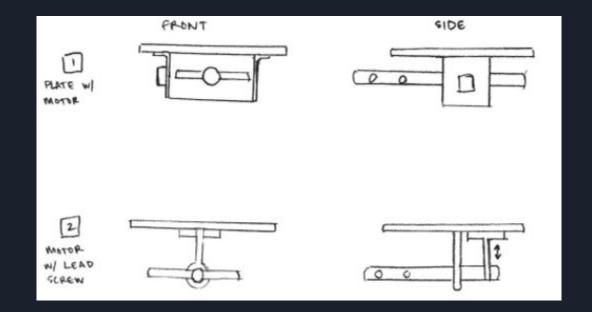


ENGINEERING REQUIREMENTS



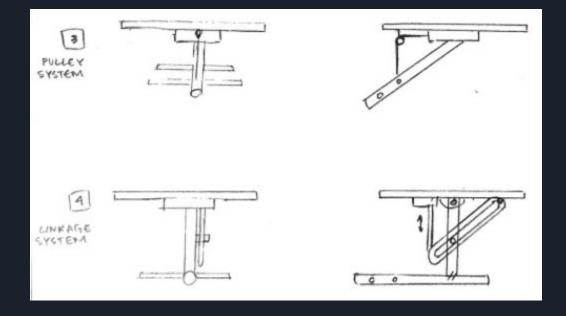


DESIGNS CONSIDERED 1-2



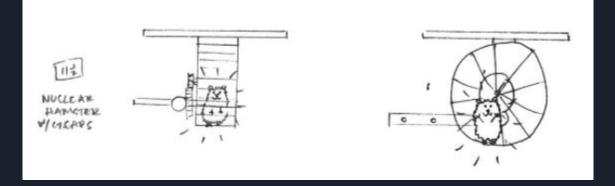


DESIGNS CONSIDERED 3-4



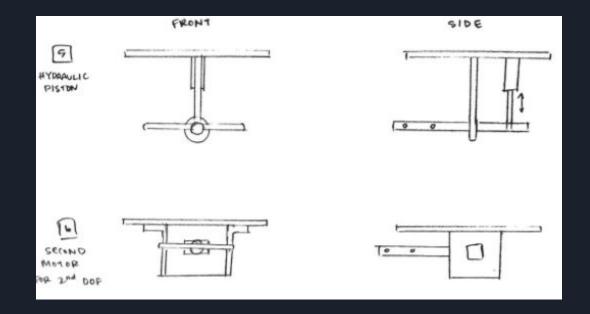


OTHER DESIGNS



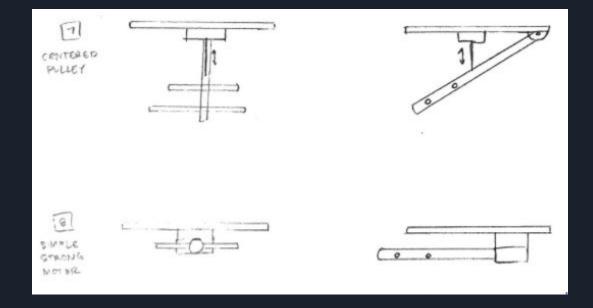


DESIGNS CONSIDERED 5-6



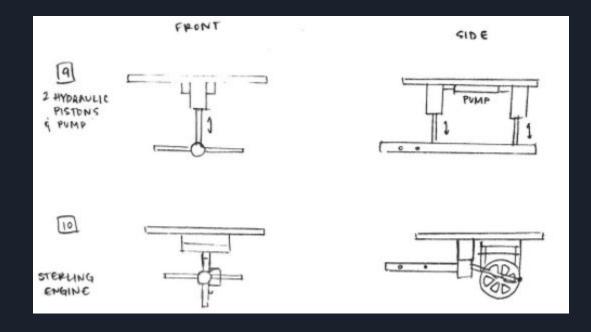


DESIGNS CONSIDERED 7-8





DESIGNS CONSIDERED 9-10





SCHEDULE TO DATE

			Week 1		Week 2				Week 3		Week 4			
Activities	Responsible Party	9/11	9/13	9/15	9/18	9/20	9/22	9/25	9/27	9/29	10/2	10/4	10/6	
1.) Project Research	All													
2.) Contact Customer	Kaitlyn Barr													
3.) Meet with Customer	All													
4.) Write Background	Kalli Albright													
5.) Customer Requirements	Daniel Johnson													
6.) Engineering Requirements	Dustin Branges													
7.) House of Quality	Kaitlyn Barr													
8.) Existing Designs	All													
9.) Black Box Model	Dustin Branges													
10.) Functional Model	Kalli Albright													
11.) Subsystems	Daniel Johnson													
12.) Designs Considered	All													
13.) Design Selected	All													
14.) Presentation	Kaitlyn Barr													
14.) Preliminary Report Editing	All									1				



SCHEDULE 10/9 - 11/3

	12		Week	5	90 - E	8	Week 6	5			Week 7			Week 8	1
Activities	Responsible Party	10/9	10/11	1 10/	13	10/16	10/18	10/20	10 /	23	10/25	10 / 27	10/30	11/1	11/3
Peer Evaluations	All														
Analytical Analyses Team Memo	All														
Individual Analyses	All									_					1.
Design Description	Kaitlyn Barr								1		-				0.
Description of Prototype Fabrication	Daniel Johnson												1		1
Proof of Concept	Kalli Albright								1						
Testing Procedures	Dustin Branges												1		
Programming Simulation	Dustin Branges								(1000
Operator Procedures	Kalli Albright											_	1		
Bill of Materials	Daniel Johnson														1
Gantt Chart for Next Semester	Kaitlyn Barr			-					1			-			
Final Report Editing	All														



SCHEDULE 11/3 - 12/15

	8	Week 10				Week 11			Week 12			Week 13			Week 14		
Activities	Responsible Party	11/13	3 11 / 1	5 11 /	17	11 / 20	11/22	11/24	11/27	11/29	12/1	12/4	12/6	12/8	12/11	12/13	12/15
Peer Evaluations 2	All																
Analytical Analyses Team Memo 2	All																
Individual Analyses 2	All																
Final CAD Package and BOM	All)								
Final Prototypes Summary	Kaitlyn Barr		1														
Final Proposal Revision	All																
Peer Evaluations 3	All														9	8	



BUDGET

- Allowed \$1,000
- Target < \$500

ІТЕМ	QUANTITY	UNIT COST
Arduino Parts	N/A	\$130.00
Motor	1	\$100.00
FTDI Cable	1	\$20.00
3D Printing Costs	\$0.10/gram	\$100.00
Fasteners	N/A	\$50.00
Total		\$400.00

Anticipated Costs



QUESTIONS

- Any requirements you would add?
- Are there any designs you prefer?
- Any changes you would make to designs considered?